

# Assia Benbihi

**Interests:** 3D Computer Vision, Reconstruction, Mapping, Localization, SLAM, Scene Understanding

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github.com/abenbihi

References: Cédric Pradalier, Matthieu Geist, Torsten Sattler

## Education

**PhD, Computer Vision and Machine Learning** CentraleSupélec, UMI2958 GeorgiaTech-CNRS Metz, France, 05/20

**Master of Electrical and Computer Engineering** Georgia Institute of Technology Atlanta, Georgia, 12/16

**Master of Science in Telecommunication Engineering** Telecom SudParis Paris, France, 06/15

**Bachelor in Maths and Physics ('Classe prepa')** Lycee Hoche Versailles, France, 06/13

## Publications

A complete list is available [abenbihi.github.io/#publications](https://abenbihi.github.io/#publications).

**EdgeGaussians – 3D Edge Mapping via Gaussian Splatting** K Chelani, A Benbihi, T Sattler, F Kahl, Preprint 2024

**Obfuscation Based Privacy Preserving Representations are Recoverable Using Neighborhood Information** K

Chelani\*, A Benbihi\*, F Kahl, T Sattler, Z Kukelova Preprint 2024

**Comparative Evaluation of Reconstruction Methods for Object Pose Estimation** V Burde\*, A Benbihi\*, P Burget, T Sattler, Preprint 2024

**Differentiable Product Quantization for Memory Efficient Camera Relocalization** Z Laskar, I Melekhov, A Benbihi, S Wang, J Kannala ECCV24

**Object-Guided Day-Night Visual Localization in Urban Scenes** A Benbihi, C Pradalier, O Chum, ICPR 2022

**Image-Based Place Recognition on Bucolic Environment Across Seasons From Semantic Edge Description**

A Benbihi, S Arravechia, M Geist, C Pradalier, ICRA 2020

**ELF: Embedded Localisation feature in pre-trained CNN** A Benbihi, M Geist, C Pradalier, ICCV 2019

**Semantic Nearest Neighbor Fields Monocular Edge Visual-Odometry** X Wu, A Benbihi, A Richard, C Pradalier

**Semi-Supervised Domain Adaptation with Representation Learning for Semantic Segmentation across**

**Time** A Benbihi, M Geist, C Pradalier, ICONIP 2019

## Experience

**Postdoc Researcher in 3D Vision** (3D reconstruction, Localization, Scene Understanding) - CIIRC, Prague 04/23-

**Niantic** (Visual Localization) Research Intern 07/22-11/22

**Postdoc Researcher** (Localization and Mapping) CTU, Prague 05/20-06/22

**Thales Research Software Engineer** 05/17-05/20

I develop a software prototype to automate visual inspection on low-contrast images with few features (C++).

**Thales Research Software Architect Intern** 01-07/16

I designed and developed a prototype of large-scale searchable encryption from a theoretical paper (C++).

## Teaching and Supervision

**Algorithms class:** master level class at CVUT (description [here](#))

**Supervision:** Bachelor, Master, PhD.

## Honours

**Outstanding reviewer:** ICCV21, ECCV22, Neurips23

**Andre Blanc-Lapierre Award; Fondation Mines-Telecom Award** Ranking: 2nd 2016

## Software

Nonexhaustive list of libraries/tools I am fluent with: COLMAP, OpenCV, Tensorflow, Pytorch, ROS, NerfStudio

Open Source Contribution

**Goma** (C++ geometry library for vanishing point estimation, plane segmentation and image rectification)

**WASABI** (Python) Research code for image retrieval from semantic edge geometric features.

**ELF** (Python) Research code for image feature matching.

**Scikit-learn** (Python) Functional tests.

## Leadership / Community Service

**Website Chair 3DV 2022**

**Program Committee:** CVPR, ICCV, ECCV, 3DV, ICRA, IROS, ICLR, NeurIPS